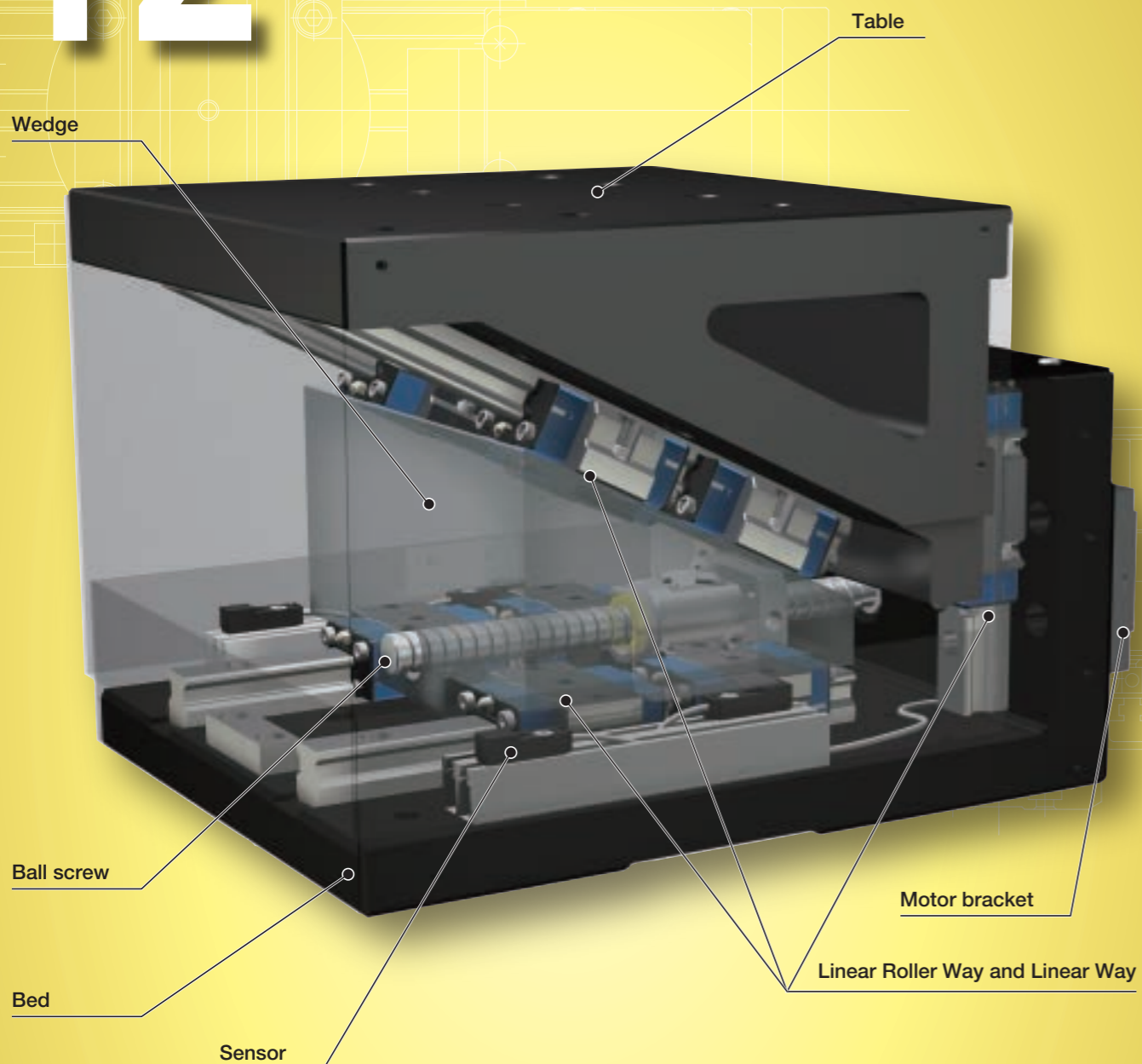
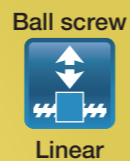


**TZ**

# TZ



## Major product specifications

Driving method	Precision ball screw
Linear motion rolling guide	Linear Roller Way (roller type) Linear Way (ball type)
Built-in lubrication part	Lubrication part "C-Lube" is built-in (TZ...H and TZ...X)
Material of table and bed	Aluminum extruded material (Alumite)
Sensor	Provided as standard

## Accuracy

Positioning repeatability	±0.001
Positioning accuracy	0.005
Lost motion	0.001
Parallelism in table motion A	-
Parallelism in table motion B	-
Attitude accuracy	-
Straightness	-
Backlash	-

unit: mm

# Points

## 1 Compact precision elevating table

This is an elevating table for performing compact yet high precision vertical positioning with unique wedge mechanism adopted.

## 2 Two types and two sizes selectable depending on the usage

There are two types consisting of high precision and high rigidity type with roller-type linear motion rolling guide incorporated and standard type superior in cost performance, and two sizes of □120mm and □200mm in dimensions of table are prepared for respective types. Two kinds of wedge reduction ratio are prepared, thus enabling vertical positioning of up to 24mm in stroke.

## 3 Installation of linear encoder enables the positioning of a rank higher level.

Specifying an optional linear encoder attached unit and performing the fully-closed loop control enables the positioning of even higher precision.

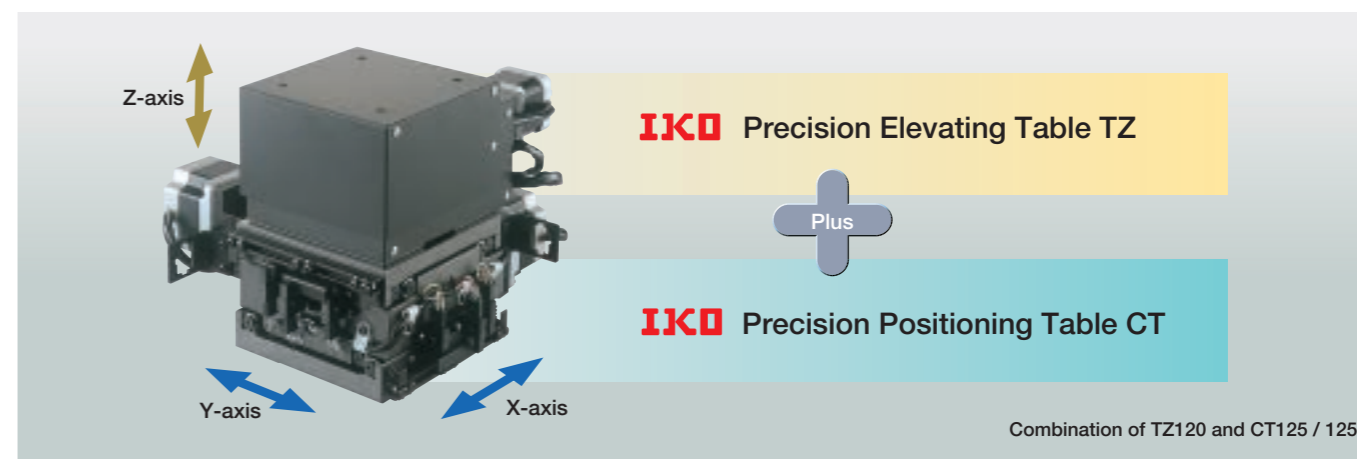
## 4 Sensor provided as standard

Limit sensor and origin / pre-origin sensors are provided as standard. The sensor is compactly built in the main unit, thus facilitating the incorporation into a machine or device.

## 5 Available as multi-axis configured Z-axis

Placing the unit on a slide table of precision positioning table makes the unit available as Z-axis positioning mechanism of the multi-axis table.

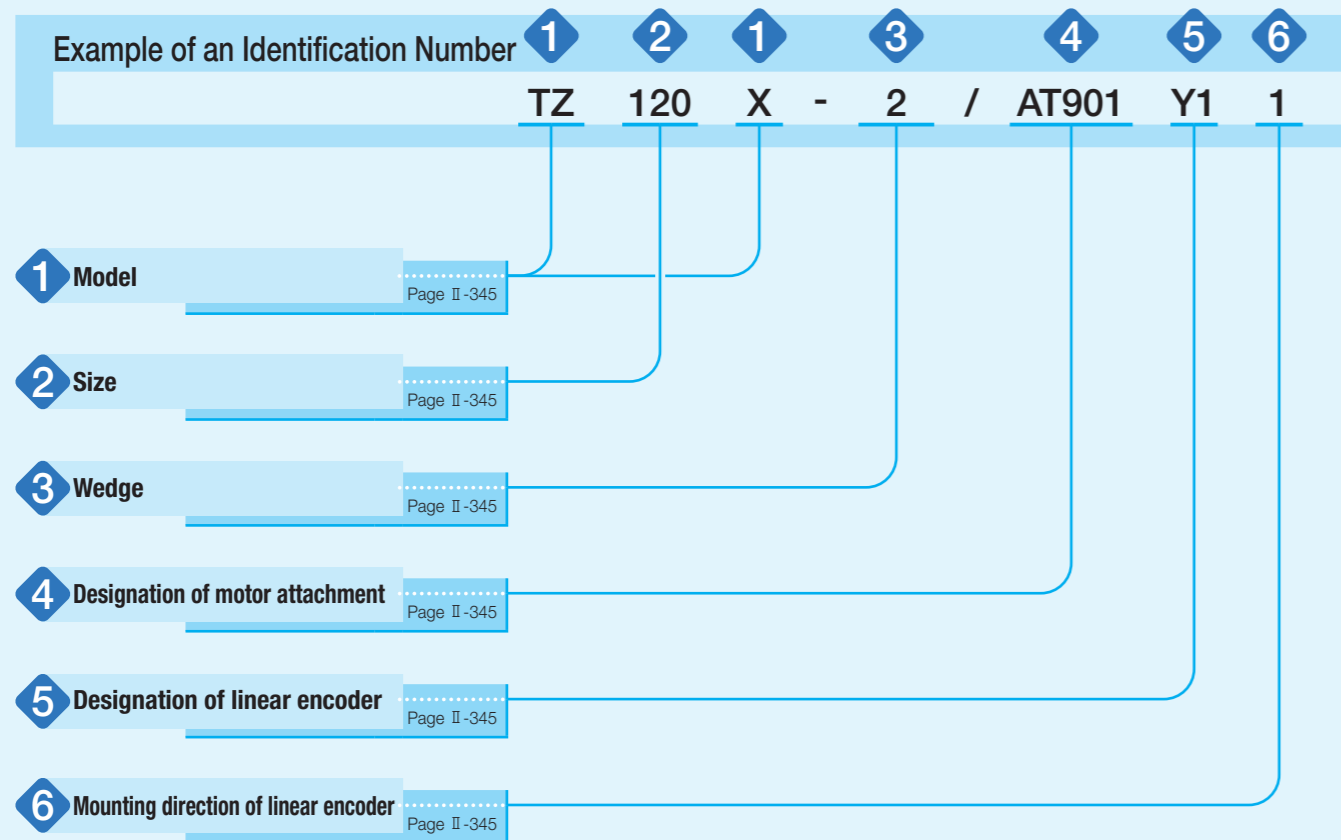
## Example of combination with XYZ positioning table using the Precision Elevating Table TZ



## Variation

Shape	Model and size	Table width (mm)	Linear motion rolling guide type	Wedge reduction ratio
	TZ120 -2	□120	Ball type	1 : 2
	TZ120 -4			1 : 4
	TZ120X-2		Roller Type	1 : 2
	TZ120X-4			1 : 4
	TZ200H-2	□200	Ball type	1 : 2
	TZ200H-4			1 : 4
TZ200X-2	Roller Type		1 : 2	
TZ200X-4			1 : 4	

# Identification Number



# Identification Number and Specification

<b>1 Model</b>	TZ : Precision Elevating Table (applicable to size 120) TZ··H: Precision Elevating Table (applicable to size 200) TZ··X: Precision Elevating Table, high precision and high rigidity type (applicable to size 120, 200)
<b>2 Size</b>	120: Table size □120mm 200: Table size □200mm
<b>3 Wedge</b>	2: Wedge reduction ratio 1 : 2 4: Wedge reduction ratio 1 : 4  This ratio indicates the reduction ratio of vertical travel distance to the ball screw feed rate.
<b>4 Designation of motor attachment</b>	As for a motor attachment, select it from the list of Table 1.  · Motor should be prepared by customer. · Please specify motor attachment applicable to motor for use. · A coupling shown in Table 2 is mounted on the main body before shipment. However, the final position adjustment should be made by customer since it is only temporarily fixed. · When specifying an AC servomotor attachment, an origin sensor is not provided.
<b>5 Designation of linear encoder</b>	No symbol: Without linear encoder When specifying the linear encoder, see Table 3.  · "With linear encoder" is only applicable to AC servomotors of TZ··H and TZ··X. For applicable models and motor attachments, see Table 1.
<b>6 Mounting direction of linear encoder</b>	No symbol: On the right as viewed from the side opposite the motor 1 : On the left as viewed from the side opposite the motor  · The mounting direction of the linear encoder and pull-out direction of the sensor cord are the same.

Table 1 Application of motor attachment

Type	Motor model			Flange size mm	Motor attachment			
	Manufacturer	Series	Model		Rated output W	TZ120 TZ120X	TZ200H TZ200X	
AC servo motor	YASKAWA ELECTRIC CORPORATION	Σ-V	SGMJV-A5	50	□40	AT901	—	
			SGMAV-A5			AT901	—	
			SGMJV-01	100		AT901	AT902	
			SGMAV-01			AT901	AT902	
			SGMAV-C2			—	AT902	
	Mitsubishi Electric Corporation	J3	HF-MP053	50		AT901	—	
			HF-KP053			AT901	—	
			HF-MP13	100		AT901	AT902	
			HF-KP13			AT901	AT902	
	Panasonic Corporation	MINAS A5	MSMD5A	50		□38	AT903	—
			MSME5A				AT903	—
			MSMD01	100			AT903	AT904
MSME01			AT903		AT904			
Stepper motor	ORIENTAL MOTOR Co., Ltd.	α step	AR46	50	□42	AT905	—	
			AR66		□60	—	AT906	
			AR69		□60	—	AT906	
			AS46		□42	AT907	—	
			AS66		□60	—	AT908	
			AS69		□60	—	AT908	
		RK CRK	RK54 · CRK54	□42	AT907	—		
			RK56 · CRK56 (1)	□60	—	AT908		

Note (1) Applicable to the outer diameter φ8 of motor output shaft.  
Remark: For detailed motor specifications, please see respective motor manufacturer's catalog.

Table 2 Coupling models

Motor attachment	Coupling models	Manufacturer	Coupling inertia $J_c$ ×10 <sup>-5</sup> kg·m <sup>2</sup>
AT901	UA-20C-8× 8	Sakai Manufacturing Co., Ltd	0.086
AT902	UA-25C-8× 8	Sakai Manufacturing Co., Ltd	0.29
AT903	UA-20C-5× 8	Sakai Manufacturing Co., Ltd	0.086
AT904	UA-25C-8× 8	Sakai Manufacturing Co., Ltd	0.29
AT905	UA-20C-5× 6	Sakai Manufacturing Co., Ltd	0.086
AT906	UA-25C-8×10	Sakai Manufacturing Co., Ltd	0.29
AT907	UA-20C-5× 5	Sakai Manufacturing Co., Ltd	0.086
AT908	UA-25C-8× 8	Sakai Manufacturing Co., Ltd	0.29

Remark: For detailed coupling specifications, please see respective manufacturer's catalog.

Table 3 Linear encoder models

Item	Target models			TZ200H, TZ200X		
	TZ120X			TZ200H, TZ200X		
Designation code of linear encoder	Y1	J1	P1	Y2	J2	P2
Manufacturers of compatible drivers	YASKAWA ELECTRIC CORPORATION	Mitsubishi Electric Corporation	Panasonic Corporation	YASKAWA ELECTRIC CORPORATION	Mitsubishi Electric Corporation	Panasonic Corporation
Manufacturer	Renishaw plc			Renishaw plc		
Linear encoder head	T1031-30A			RGH20B30L00A	RGH20Y30D33A	
Linear encoder	A-9705-0004			A-9660-0080		
Interface	Ti0000A00V	Ti0200A04A		—		
Reference mark	—			A-9561-0065		

# Specifications

**Table 4 Specifications**

Model and size	Wedge reduction ratio	Ball screw lead mm	Resolution <sup>(1)</sup> $\mu\text{m/pulse}$	Stroke length mm
TZ120 -2	1 : 2	4	2	10
TZ120 -4	1 : 4		1	5
TZ120X-2	1 : 2		2.0 (0.1)	10
TZ120X-4	1 : 4		1.0 (0.1)	5
TZ200H-2	1 : 2	5	2.5 (0.1)	24
TZ200H-4	1 : 4		1.25 (0.1)	12
TZ200X-2	1 : 2		2.5 (0.1)	24
TZ200X-4	1 : 4		1.25 (0.1)	12

Note <sup>(1)</sup> The resolution indicates a value when fraction sizes of the motor are 1,000 pulses/rev.  
 Remark: The values in ( ) indicate values with linear encoder and J3 series of Mitsubishi Electric Corporation or MINAS A5 system of Panasonic Corporation selected. If the  $\Sigma$ V system of YASKAWA ELECTRIC CORPORATION is selected, it should be 0.078125  $\mu\text{m/pulse}$ .

**Table 5 Accuracy**

Model and size	Wedge reduction ratio	Positioning repeatability	Positioning accuracy	Lost motion	Parallelism in table elevating	Squareness in table elevating
TZ120 -2	1 : 2	$\pm 0.001$	—	—	—	—
TZ120 -4	1 : 4		—	—	—	—
TZ120X-2	1 : 2	$\pm 0.001$	—	0.001	0.010	0.010
TZ120X-4	1 : 4		(0.005)	—	—	—
TZ200H-2	1 : 2	$\pm 0.001$	—	—	—	—
TZ200H-4	1 : 4		(0.005)	—	—	—
TZ200X-2	1 : 2	$\pm 0.001$	—	0.001	0.010	0.010
TZ200X-4	1 : 4		(0.005)	—	—	—

Remark: The values in ( ) indicate values with a linear encoder.

**Table 6 Maximum speed**

Model and size	Wedge reduction ratio	Ball screw lead mm	Maximum speed mm/s	
			AC servomotor	Stepper motor
TZ120 -2	1 : 2	4	100	60
TZ120 -4	1 : 4		50	30
TZ120X-2	1 : 2		100	60
TZ120X-4	1 : 4		50	30
TZ200H-2	1 : 2	5	125	75
TZ200H-4	1 : 4		62.5	37.5
TZ200X-2	1 : 2		125	75
TZ200X-4	1 : 4		62.5	37.5

Remark: To measure the practical maximum speed, it is required to consider operation patterns based on the motor to be used and load conditions.

**Table 7 Maximum carrying mass**

Model and size	Wedge reduction ratio	Maximum carrying mass	
		Horizontal	Vertical
TZ120	1 : 2	36	10
	1 : 4	36	10
TZ120X	1 : 2	94	10
	1 : 4	146	10
TZ200H	1 : 2	109	9
	1 : 4	109	10
TZ200X	1 : 2	147	9
	1 : 4	160	10

**Table 8 Specifications of ball screw**

Model and size	Shaft dia.	Overall length
TZ120	8	105
TZ120X	8	168
TZ200H	12	215
TZ200X	12	215

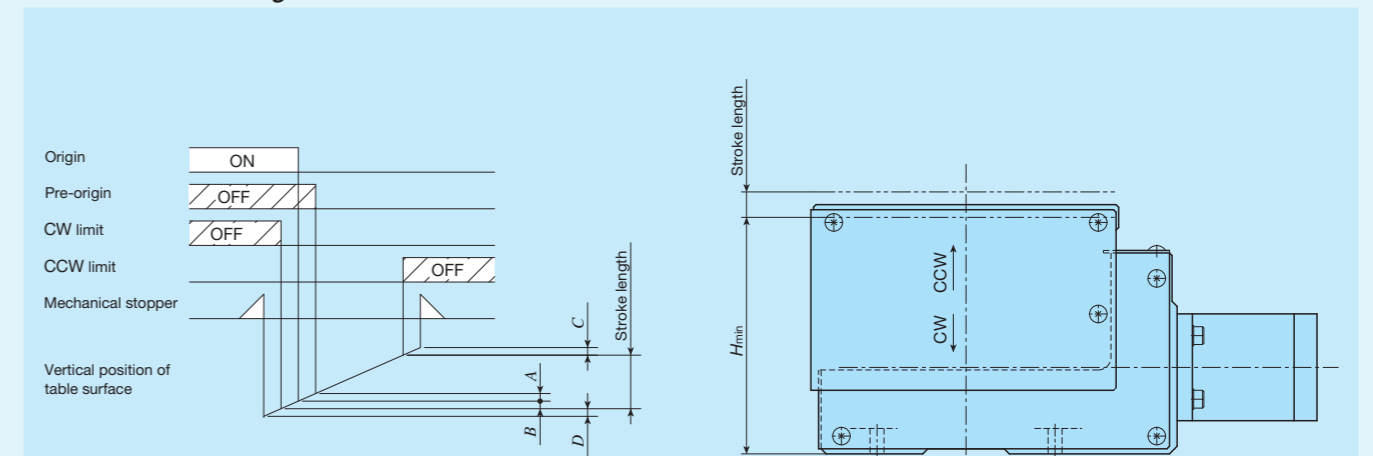
unit: mm

**Table 9 Table inertia and starting torque**

Model and size	Wedge reduction ratio	Table inertia $J_T$ $\times 10^{-5}\text{kg}\cdot\text{m}^2$	Starting torque $T_s$ N·m
TZ120 -2	1 : 2	0.076	0.03
TZ120 -4	1 : 4	0.061	0.02
TZ120X-2	1 : 2	0.076	0.03
TZ120X-4	1 : 4	0.064	0.02
TZ200H-2	1 : 2	0.581	0.07
TZ200H-4	1 : 4	0.473	0.06
TZ200X-2	1 : 2	0.581	0.07
TZ200X-4	1 : 4	0.473	0.06

# Sensor Specification

**Table 10 Sensor timing chart**



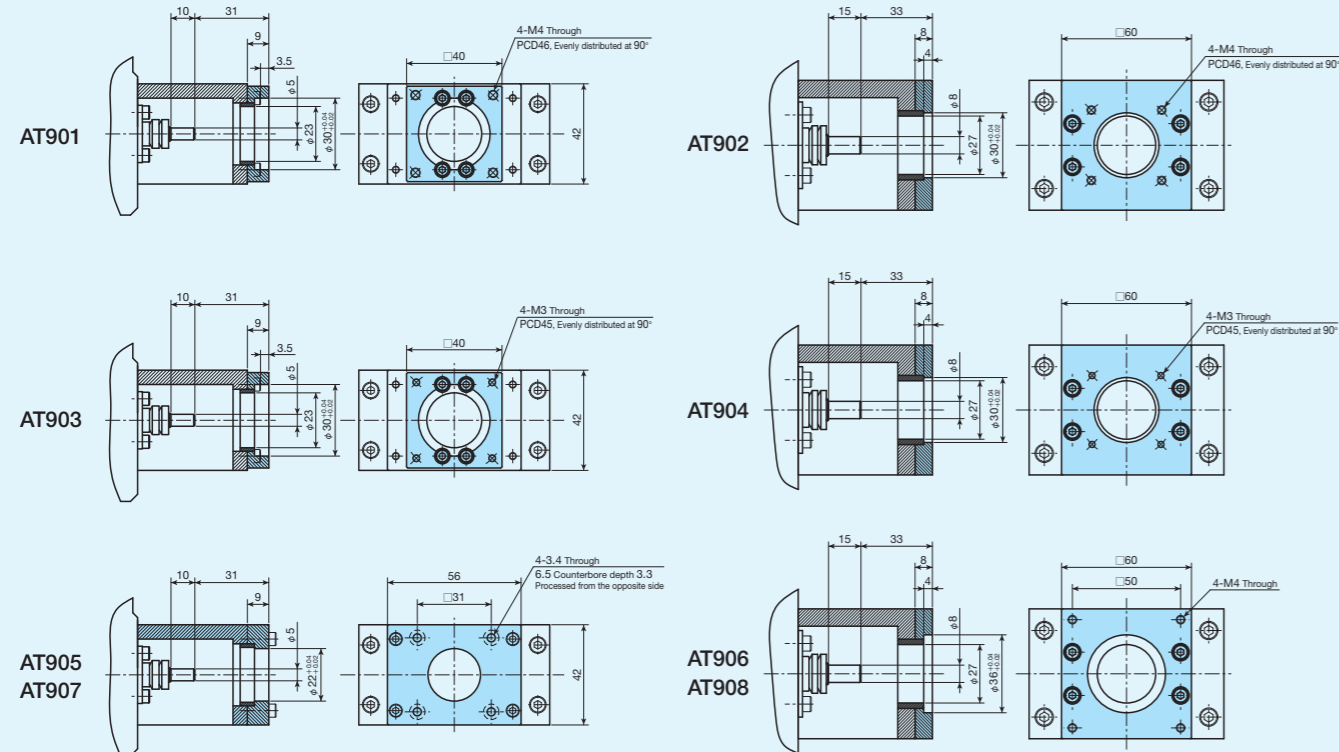
unit: mm

Identification number	A	B	C	D
TZ120 -2	1	1	1	1
TZ120X-2	1	1	1	1
TZ120 -4	0.5	0.5	0.5	0.5
TZ120X-4	0.5	0.5	0.5	0.5
TZ200H-2	1.5	1	2.5	1
TZ200X-2	1.5	1	2.5	1
TZ200H-4	0.75	0.5	1.25	0.5
TZ200X-4	0.75	0.5	1.25	0.5

# Dimensions of Motor Attachment

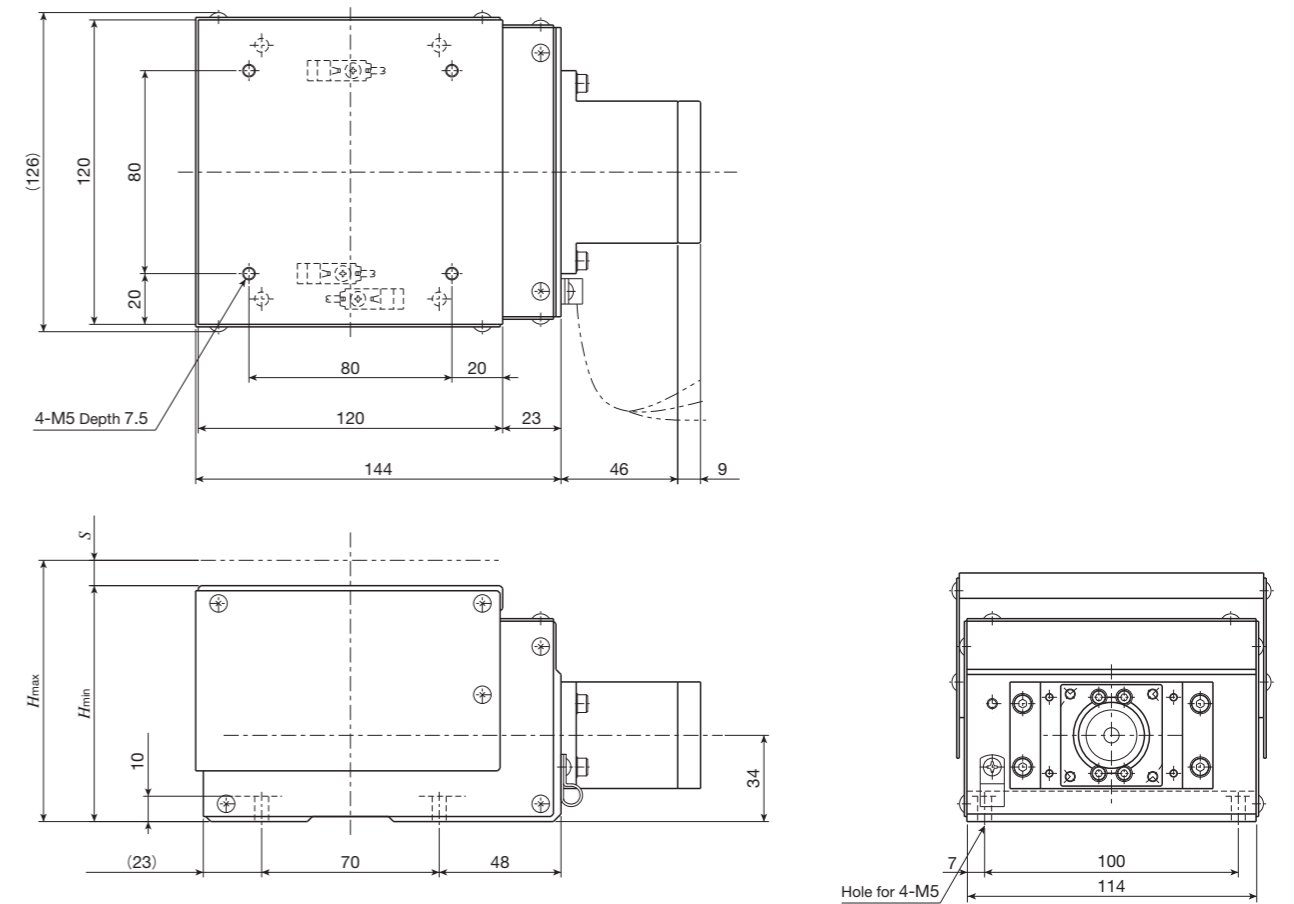
TZ120, TZ120X

TZ200H, TZ200X



# IKO Precision Elevating Table TZ

TZ120



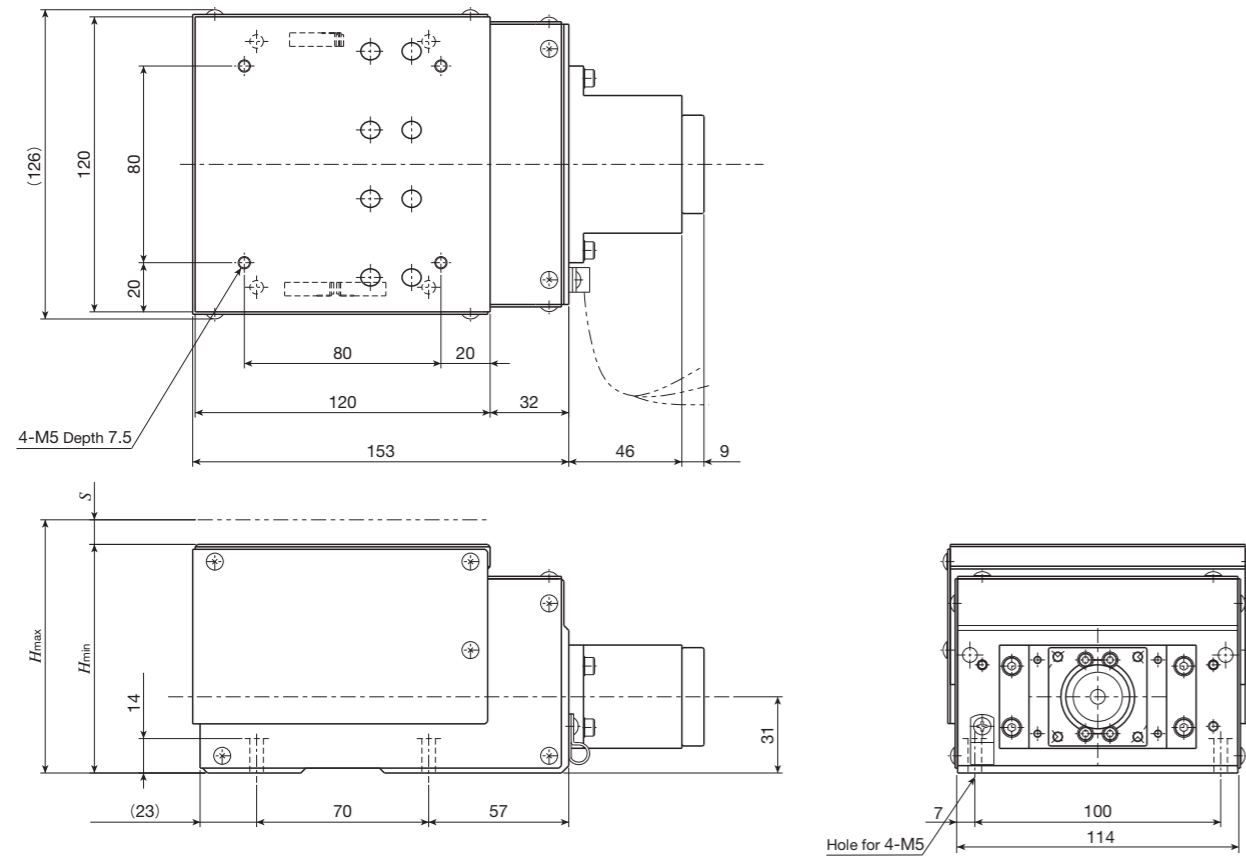
unit: mm

Identification number	Wedge reduction ratio	Mass (Ref.) kg	Mounting holes of bed		Stroke length $S$
			$H_{min}$ (CW limit position)	$H_{max}$ (CCW limit position)	
TZ120-2	1 : 2	3.8	93	103	10
TZ120-4	1 : 4	3.4	84.5	89.5	5



# IKO Precision Elevating Table TZ

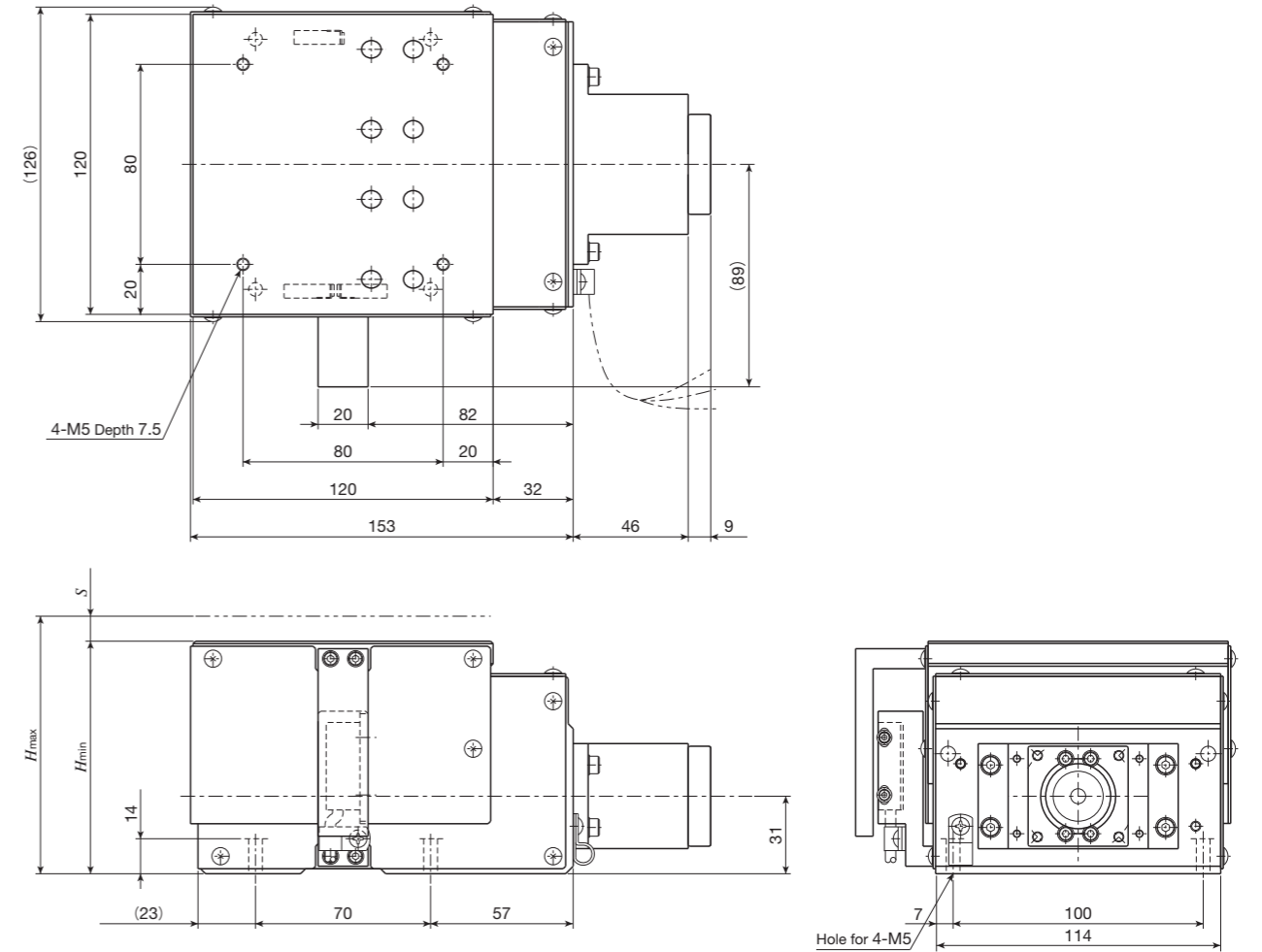
## TZ120X without linear encoder



unit: mm

Identification number	Wedge reduction ratio	Mass (Ref.) kg	Mounting holes of bed		Stroke length S
			$H_{min}$ (CW limit position)	$H_{max}$ (CCW limit position)	
TZ120X-2	1 : 2	3.8	93	103	10
TZ120X-4	1 : 4	3.4	84.5	89.5	5

## TZ120X with linear encoder

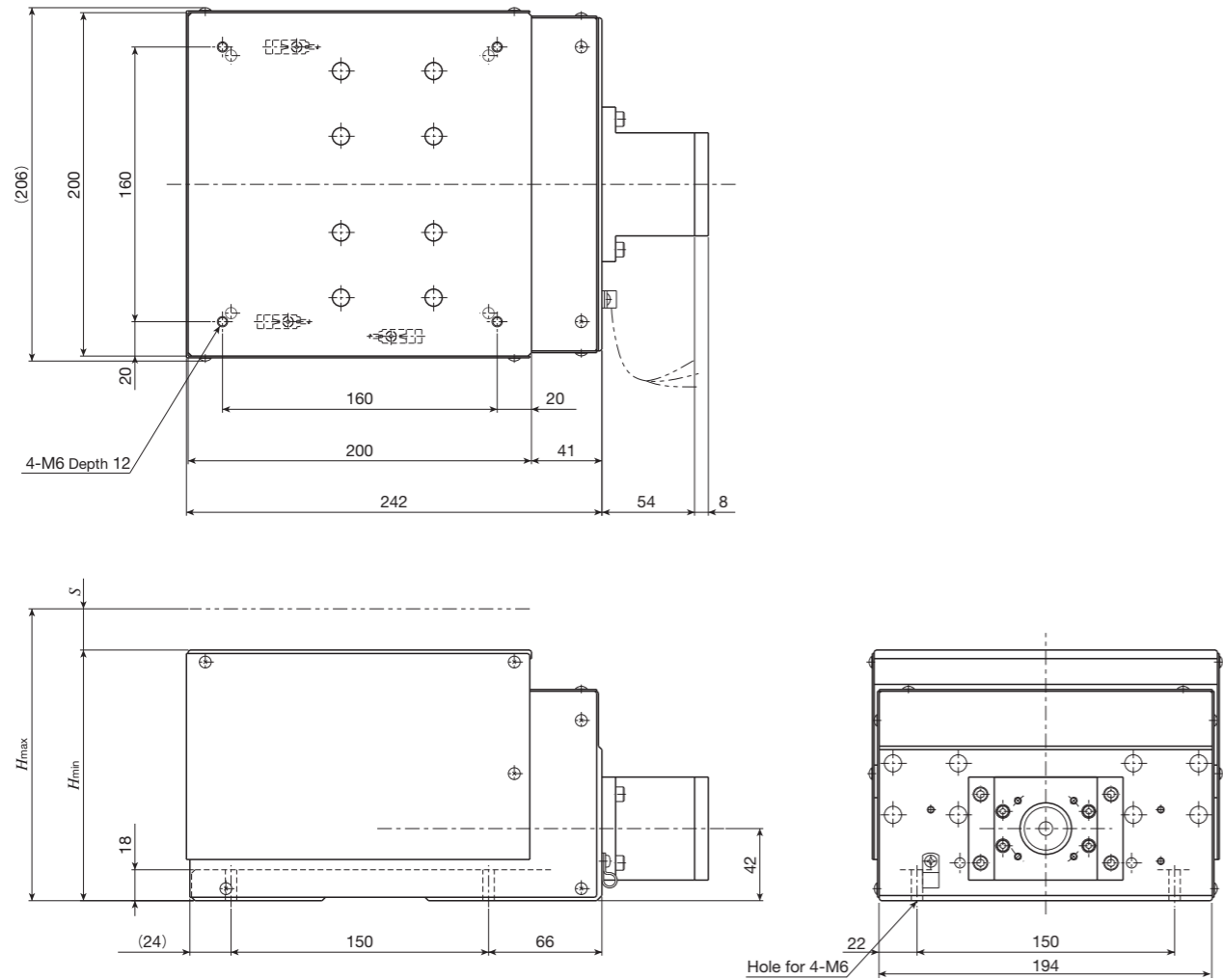


unit: mm

Identification number	Wedge reduction ratio	Mass (Ref.) kg	Mounting holes of bed		Stroke length S
			$H_{min}$ (CW limit position)	$H_{max}$ (CCW limit position)	
TZ120X-2/F	1 : 2	4.5	93	103	10
TZ120X-4/F	1 : 4	4.1	84.5	89.5	5

# IKO Precision Elevating Table TZ

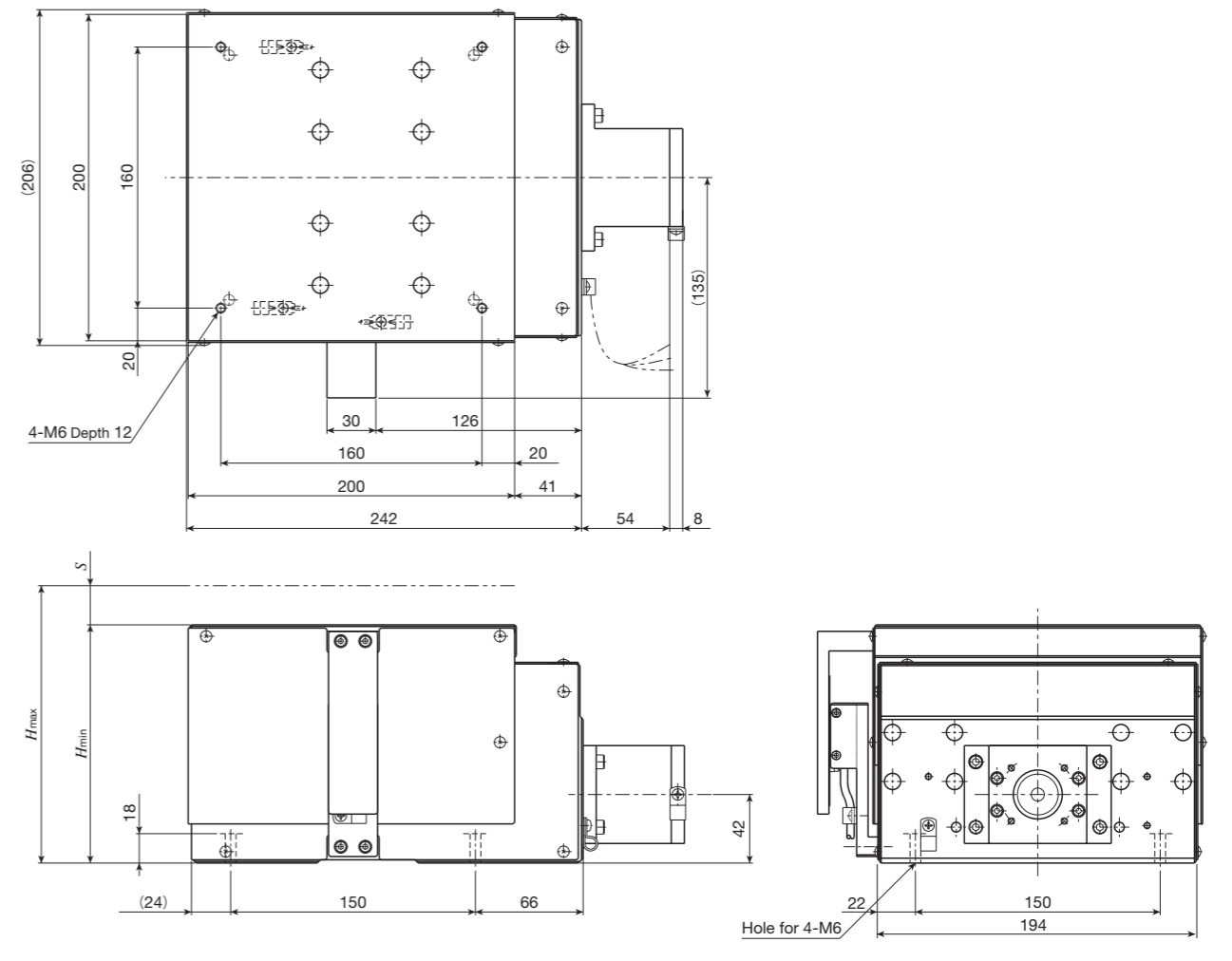
## TZ200H, TZ200X without linear encoder



unit: mm

Identification number	Wedge reduction ratio	Mass (Ref.) kg	Mounting holes of bed		Stroke length S
			$H_{min}$ (CW limit position)	$H_{max}$ (CCW limit position)	
TZ200H-2	1 : 2	13.2	146	170	24
TZ200H-4	1 : 4	12.2	132	144	12
TZ200X-2	1 : 2	13.3	146	170	24
TZ200X-4	1 : 4	12.3	132	144	12

## TZ200H, TZ200X with linear encoder



unit: mm

Identification number	Wedge reduction ratio	Mass (Ref.) kg	Mounting holes of bed		Stroke length S
			$H_{min}$ (CW limit position)	$H_{max}$ (CCW limit position)	
TZ200H-2/F	1 : 2	14.2	146	170	24
TZ200H-4/F	1 : 4	13.2	132	144	12
TZ200X-2/F	1 : 2	14.3	146	170	24
TZ200X-4/F	1 : 4	13.3	132	144	12