# SA...DE

Crossed roller bearing

Moving magnet

Mechanical stopper

Stator coil

Stator coil

Moving magnet

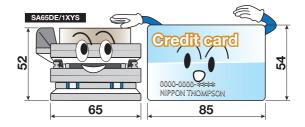
Using a Linear Way L miniature linear motion rolling guide in the linear motion guiding parts and Crossed Roller Bearing in the rotation guiding parts respectively and adopting direct drive method in the drive section, this is an alignment stage for achieving low profile and compact  $XY\theta$  motion.

### • Flexible combination of XY $\theta$

X-table for linear movement and  $\theta$ -table serving as rotary positioning section are listed on lineup as basic configuration. Combination of X-axis and  $\theta$ -axis and alignment table for XY-axis can be easily configured.

### Thin and compact

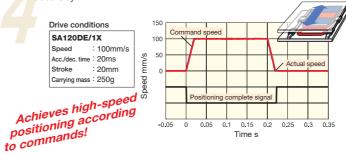
Coreless linear motor, Linear Way L and Crossed Roller Bearing are adopted. As compared with ball screw-driven stage, extremely low profile is achieved.

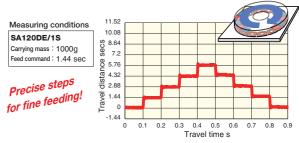


# XY-axis $X\theta$ -axis $XY\theta$ -axis

### High resolution and high responsiveness

Performing full-closed loop control of direct drive-type stage with high resolution linear encoder built-in has achieved high resolution and high accuracy.





### Alignment Stage SA specification list

	SA65I	DE/X	SA1	20DE/X	SA200	DE/X	SA65DE/S	SA120DE/S	SA200DE/S
Model and size			V						
Sectional shape		65 £	120		8 <b>F</b>	200	65	120	200
Maximum thrust N	25	5	70		400 (250)		Max. torque 0.5N·m	Max. torque 2.0N·m	Max. torque 8.0 (6.0)N·m
Rated thrust N	3	3.5	15		70		Rated torque 0.06N·m	Rated torque 0.4N·m	Rated torque 2.0N·m
Maximum load mass kg	2.4		5.9		30.0 (20.0)		2.2	6.8	21.2 (17.1)
Effective stroke length mm	10		20		20		Effective operating angle 50degree	Effective operating angle 60degree	Effective operating angle 280degree
Resolution $\mu$ m	0.1	0.5	0.1	0.5	0.1	0.5	0.64sec 5625pulse/deg	0.36sec 10000pulse/deg	0.25sec 14400pulse/deg
Maximum speed mm/s	270	500	270	800	270	800	720deg/sec	400deg/sec	270deg/sec
Positioning repeatability $\mu$ m	±0.5		±C	).5	±0.5		±1.3sec	±0.8sec	±0.5sec

Remark: Numbers in parentheses indicate values when used with an ADVA-R5ML driver.

# Major product specifications

Driving method	Linear motor
Linear motion rolling guide and bearing	XY-axis: Linear Way (ball type) $\theta$ -axis: Crossed Roller Bearing
Lubrication	Lubrication part "C-Lube" is built-in (except for $\theta$ -axis and SA65DE/X)
Material of table and bed	High carbon steel
Sensor	Provided as standard

## **Accuracy**

Mechanical stopper

	unit: mm
Positioning repeatability	XY-axis: $\pm 0.0005$ $\theta$ -axis: $\pm 0.5 \sim 1.3$ sec
Positioning accuracy	-
Lost motion	-
Parallelism in table motion A	-
Parallelism in table motion B	-
Attitude accuracy	-
Straightness	-
Backlash	-

Linear motor drive

X-table

Linear Way

Optical linear encoder

scale head

C-Lube

**θ**-table

# Example of an Identification Number Example of an Identification Number SA 120 DE / 5 XYS R 4 Model Page II-279 Size Page II-279 Axial configuration Page II-279 Specification number Page II-279

# **Identification Number and Specification.**

Model	SA···DE: Alignment Stage SA
<b>△</b> a:	
Size	65: ☐ 65, <i>φ</i> 65
	120: □120, <i>φ</i> 120
	200: □200, ∅200
A Brookeling	
Resolution	1: 0.1 µm
	5: 0.5μm
	Specify the resolution of the encoder for X-axis or XY-axis.
	When selecting only S: $\theta$ -axis in the entry of section $\phi$ , set "No symbol" for the resolution.
<b>A</b>	
4 Axial configuration	Select an axial configuration from the list of Table 1.

### Table 1 Axial configuration and application

Axial configuration	SA65DE	SA120DE	SA200DE			
X : Only X-axis	0	0	0			
S : Only $\theta$ -axis	0	0	0			
XY : XY -based two-axis configuration	0	0	0			
XS : X θ -based two-axis configuration	0	0	0			
XYS: X. Y. and $\theta$ -based three-axis configuration	0	0	0			

5 Surface treatment	No symbol: Electroless nickel plating
	R : Black chrome surface treatment Surface treatment is performed on the surfaces of table and bed.
6 Specification number	4: Specification number 4

# **Specifications**

### Table 2.1 Specification / Performance

Identifica Item	tion number	SA65DE/1X	SA65DE/5X	SA120DE/1X	SA120DE/5X	SA200DE/1X(8)	<b>SA200DE/5X</b> (8)	
Maximum thrust (1)	N	25	5	70	70		400 (250)	
Rated thrust (2)	N	3	3.5	<b>15</b> ( <sup>7</sup> )		70		
Effective stroke length	mm	10		20		20		
Maximum load mass	kg	2.4		5.9		30.0 (20.0)		
Resolution	μm	0.1	0.5	0.1	0.5	0.1	0.5	
Maximum speed (3)(4)	mm/s	270	500	270	800	270	800	
Positioning repeatability (	<sup>5</sup> ) μm	±0.5						
Mass of moving table	kg	0.	17	1.2		3.4		
Total mass (6)	kg	0.35		2.5		7.2		
Ambient temperature and humidity in operation	d		0~40	℃ · 20~80%RH	(keep dewdrop	o free)		

Notes (1) The duration of maximum thrust is up to 1 second.

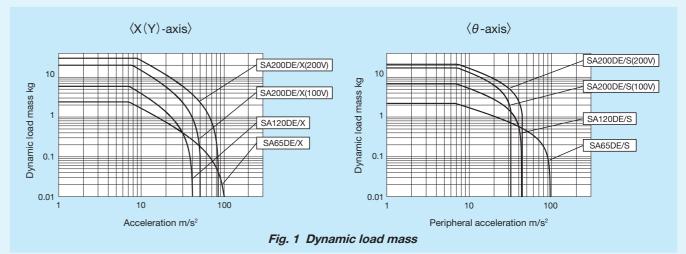
- (2) This is based on the case of mounting on a metal mating member material at an ambient temperature of 20°C.
- (3) For the case of exceeding the displayed speed, please contact IKO.
- (4) This maximum speed may not be reached depending on the maximum output frequency of the controller used, and the driver type or settings.
- (5) When the temperature of the product is constant.
- (6) Mass of the cord is not included.
- (7) The rated thrust applies within the effective stroke range.
- (8) Numbers in parentheses indicate values when used with an ADVA-R5ML driver.

### Table 2.2 Specification / Performance

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<u>Identificat</u>	Identification number		SA120DE/S	<b>SA200DE/S</b> ( <sup>7</sup> )	
Maximum torque (1)	N∙m	0.5	2.0	8.0 (6.0)	
Rated torque (2)	N∙m	0.06	0.4	2.0	
Maximum load mass	kg	2.2	6.8	21.2 (17.1)	
Effective operating angle	degree	50	60	280	
Resolution	sec	0.64	0.36	0.25	
nesolution	pulse/degree	5 625	10 000	14 400	
Maximum speed (3)(4)	degree/sec	720	400	270	
Positioning repeatability (5	sec	±1.3	±0.8	±0.5	
Inertia moment of moving table	kg·m²	0.00012	0.002	0.013	
Total mass (6)	kg	0.5	2	6	
Ambient temperature and humidity in operation		0~40°C · 20~80%RH (keep dewdrop free)			

Notes (1) The duration of maximum torque is up to 1 second.

- (2) This is based on the case of mounting on a metal mating member material at an ambient temperature of 20°C.
- (3) For the case of exceeding the displayed speed, please contact IKO.
- (4) This maximum speed may not be reached depending on the maximum output frequency of the controller used, and the driver type or settings.
- (5) When the temperature of the product is constant.
- (6) Mass of the cord is not included.
- (7) Numbers in parentheses indicate values when used with an ADVA-R5ML driver.



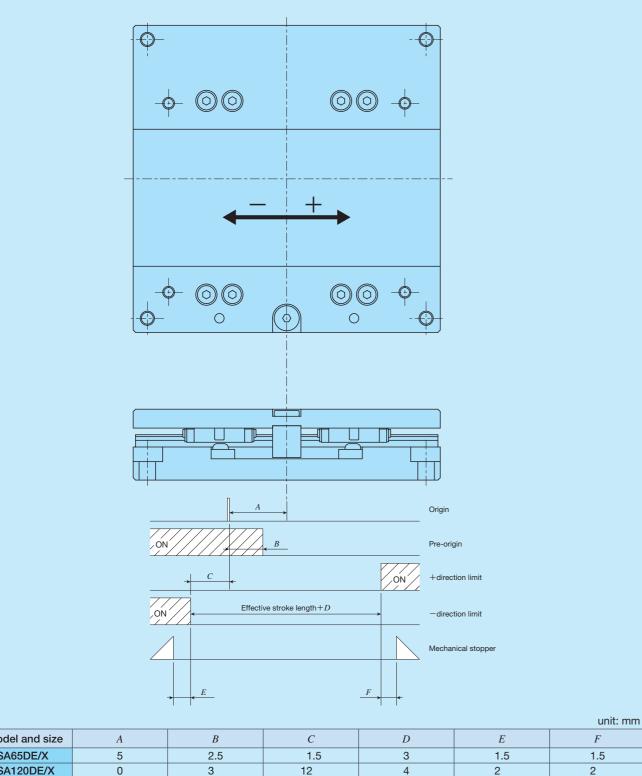
Remark: Dynamic load mass of  $\theta$ -axis is a value calculated as cube of steel. And, the acceleration is converted as value of stage periphery.

# **Mounting**

For the processing accuracy of the Precision Positioning Table mounting surface and the tightening torque of the fixing

# **Sensor Specification**

Table 3.1 Sensor timing chart for SA···DE/X (X-axis)

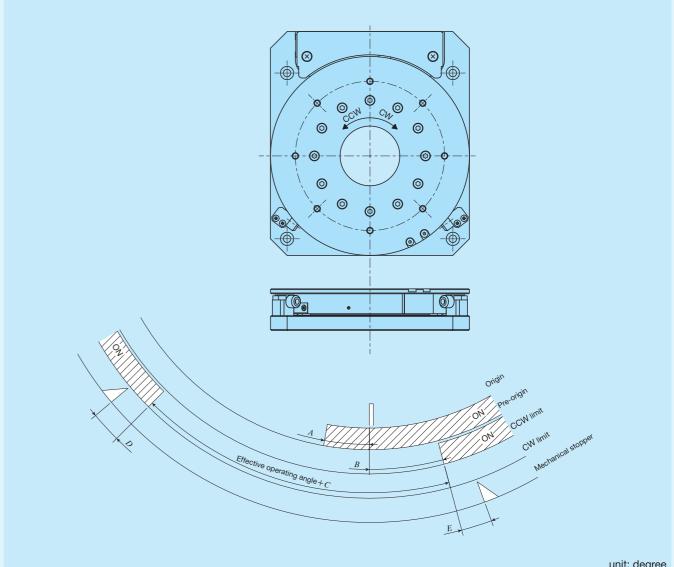


						unit. min
Model and size	A	В	С	D	E	F
SA65DE/X	5	2.5	1.5	3	1.5	1.5
SA120DE/X	0	3	12	4	2	2
SA200DE/X	0	4	10	0	5	5

Remarks 1. Respective values are for reference and are not guaranteed values. For detailed dimensions, please contact IKO.

### **Sensor Specification**

Table 3.2 Sensor timing chart for SA···DE/S (θ-axis)



					ariiti dogroo
Model and size	A	В	С	D	E
SA65DE/S	4	11	10	5	5
SA120DE/S	3	3	6	3	3
SA200DE/S	2	4	0	4	4

Remarks 1. Respective values are for reference and are not guaranteed values. For detailed dimensions, please contact IKO.

<sup>2.</sup> For detailed specifications of respective sensors, please see the section of sensor specification in General Explanation.

<sup>2.</sup> For detailed specifications of respective sensors, please see the section of sensor specification in General Explanation.

# **System Configuration**

Two series of dedicated drivers, ADVA and MR-J4, are available for the Alignment Stage SA, and the system configuration varies depending on the driver used. For ADVA, two types of specification, pulse train specification and high speed network EtherCAT specification, are available. For MR-J4, only high speed network SSCNET III/H specification is available. Table 4 shows the example of identification number for ADVA, and Table 5 shows the tables and model number of applicable MR-J4. For detailed driver specification, please see the driver specification on page II -389 to II -391.

### Table 4 Identification number for ADVA

<b>ADVA</b>	_	01NL	EC	/	SA65DE-S
(1) Model		(2)	(3)		(4)

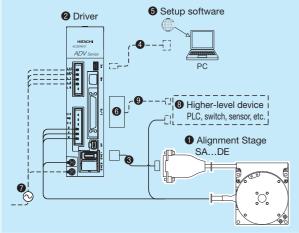
(2) Power supply voltage					
01NL Single-phase / Three-phase 200 V					
R5ML Single-phase 100 V					
(3) Command type					
No symbol	Pulse train command				
F0	EU OAT				

(4) Applicable alignment stage model		
SA65DE -S SA65DE /S		
SA65DE -X	SA65DE /X	
SA120DE -S	SA120DE /S	
SA120DE -X	SA120DE /X	
SA200DE -S2	SA200DE /S	
SA200DE -X	SA200DE /X	

Table 5 Identification numbers of SA...DE and applicable MR-J4

Identification number of table	Identification number of driver
SA65DE /S	MR-J4-10B-RJ /SA65DE -S
SA65DE /X	MR-J4-10B-RJ /SA65DE -X
SA120DE /S	MR-J4-10B-RJ /SA120DE -S
SA120DE /X	MR-J4-10B-RJ /SA120DE -X
SA200DE /S	MR-J4-10B-RJ /SA200DE -S2
SA200DE /X	MR-J4-10B-RJ /SA200DE-X

Table 6 System configuration for SA65DE, SA120DE with driver ADVA

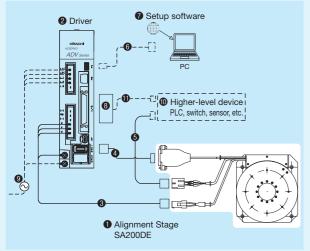


No.	Name	Identification Number
3	Encoder extension cord (2m) (1)	TAE20V4-EC02
4	PC connection cable	USB mini B cable This must be prepared by customer.
6	Setup software	ProDriveNext Please download from the official website of Hitachi Industrial Equipment Systems Co., Ltd.
6	I/O connector	TAE20R5-CN(2)
7	Power cord	This was the consequent has
8	Higher-level device	This must be prepared by customer.
9	I/O connector connection cable	Custoffier.

Notes (1) For specific cord length, please contact IKO.

(2) I/O connector TAE20R5-CN is a combined product of 10150-3000PE (connector) and 10350-52F0-008 (cover) from 3M Japan Limited.

### Table 7 System configuration for SA200DE with driver ADVA



No.	Name	Identification Number
3	Motor extension cord (3m) (1)	TAE20V3-AM03
4	Encoder extension cord (2m) (1)	TAE20V4-EC02
6	Sensor extension cord (2)	TAE10V8-LC□□
6	PC connection cable	USB mini B cable This must be prepared by customer.
0	Setup software	ProDriveNext Please download from the official website of Hitachi Industrial Equipment Systems Co., Ltd.
8	I/O connector	TAE20R5-CN(3)
9	Power cord	This way at he away are all her
0	Higher-level device	This must be prepared by customer.
•	I/O connector connection cable	customer.

Notes (1) For specific cord length, please contact IKO.

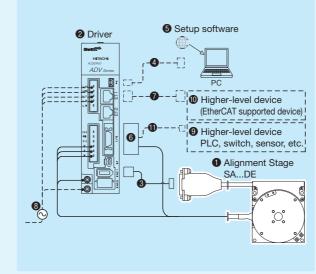
- (2) The lengths of the sensor extension cord is specified in the fields of  $\Box\Box$  located at the end of the identification number with a length from 3 to 10m in units of 1m
- (3) I/O connector TAE20R5-CN is a combined product of 10150-3000PE (connector) and 10350-52F0-008 (cover) from 3M Japan Limited.

### Setup software

To operate Alignment Stage SA, initial setting of driver parameters is required. Parameter setting for driver is performed using the setup software. It can also be used for gain adjustment and operational status check.

In the driver, the setup software and PC connection cable are not provided. These can be shared in plural drivers but at least 1 set is required. Please prepare these on your own or place an order separately according to your requirement.

Table 8 System configuration for SA65DE, SA120DE with driver ADVA...EC

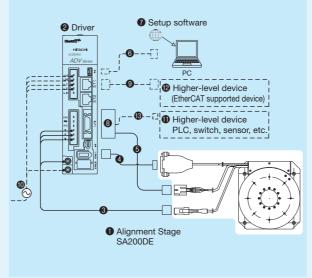


No	о.	Name	Identification Number
•	3	Encoder extension cord (2m) (1)	TAE20V4-EC02
4	9	PC connection cable	USB mini B cable This must be prepared by customer.
•	<b>5</b>	Setup software	ProDriveNext Please download from the official website of Hitachi Industrial Equipment Systems Co., Ltd.
•	3	I/O connector	TAE20V5-CN(2)
•	7	Ethernet cable	
•	3	Power cord	
e	9	Higher-level device	This must be prepared by
0	D	Higher-level device (EtherCAT supported device)	customer.
1	D	I/O connector connection cable	

Notes (1) For specific cord length, please contact IKO.

(2) I/O connector TAE20V5-CN is a combined product of 10120-3000PE (connector) and 10320-52F0-008 (cover) from 3M Japan Limited.

Table 9 System configuration for SA200DE with driver ADVA...EC

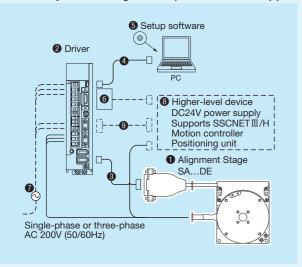


No.	Name	Identification Number
3	Motor extension cord (3m) (1)	TAE20V3-AM03
4	Encoder extension cord (2m) (1)	TAE20V4-EC02
6	Sensor extension cord (2)	TAE10V8-LC□□
6	PC connection cable	USB mini B cable This must be prepared by customer.
0	Setup software	ProDriveNext Please download from the official website of Hitachi Industrial Equipment Systems Co., Ltd.
8	I/O connector	TAE20V5-CN(3)
9	Ethernet cable	
0	Power cord	
0	Higher-level device	This must be prepared by
<b>®</b>	Higher-level device (EtherCAT supported device)	customer.
13	I/O connector connection cable	

Notes (1) For specific cord length, please contact IKO.

- (2) The lengths of the sensor extension cord is specified in the fields of  $\Box\Box$  located at the end of the identification number with a length from 3 to 10m in units of 1m.
- (3) I/O connector TAE20V5-CN is a combined product of 10120-3000PE (connector) and 10320-52F0-008 (cover) from 3M Japan Limited.

### Table 10 System configuration (SSCNET II/H supported) for SA65DE, SA120DE with driver MR-J4-10B

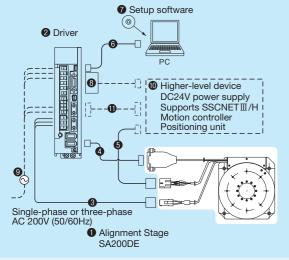


No.	Name	Identification Number
8	Encoder extension cord (2m) (1)	TAE20V6-EC02
4	PC connection cable (3m)	MR-J3USBCBL3M
6	Setup software	SW1DNC-MRC2-J
6	Connectors for input/output connection	MR-CCN1(2)
7	Power cord	This way at he was a weed by
8	Higher-level device (3)	This must be prepared by customer.
9	Connection cable for SSCNET II/H	custofflet.

Notes (1) For specific cord length, please contact IKO.

- (2) Connector for input/output connection MR-CCN1 is a combined product of 10120-3000PE (connector) and 10320-52F0-008 (cover) from 3M Japan Limited.
- (3) The higher-level devices are a motion controller, positioning unit and DC24V power supply ready for SSCNET II/H from Mitsubishi Electric Corporation.

Table 11 System configuration (SSCNET II/H supported) for SA200DE with driver MR-J4-10B

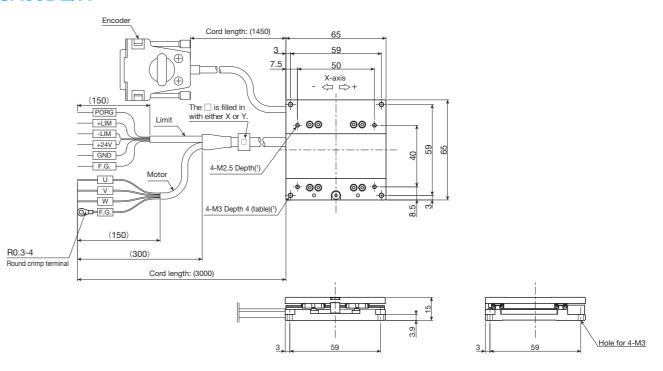


No.	Name	Identification Number
3	Motor extension cord (3m) (1)	TAE20V3-AM03
4	Encoder extension cord (2m) (1)	TAE20V6-EC02
6	Sensor extension cord (2)	TAE10V8-LC□□
6	PC connection cable (3m)	MR-J3USBCBL3M
7	Setup software	SW1DNC-MRC2-J
8	Connectors for input/output connection	MR-CCN1(3)
9	Power cord	This recent has remained him
0	Higher-level device (4)	This must be prepared by customer.
0	Connection cable for SSCNET Ⅲ/H	custoffier.

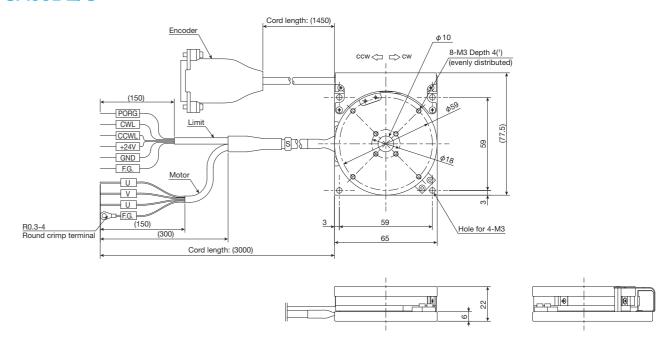
- Notes (1) For specific cord length, please contact IKO.
  - (2) The lengths of the sensor extension cord is specified in the fields of  $\Box\Box$  located at the end of the identification number with a length from 3 to 10m in units of 1m.
  - (3) Connector for input/output connection MR-CCN1 is a combined product of 10120-3000PE (connector) and 10320-52F0-008 (cover) from 3M Japan Limited.
  - (4) The higher-level devices are a motion controller, positioning unit and DC24V power supply ready for SSCNET Ⅲ/H from Mitsubishi Electric Corporation.



### SA65DE/X



### SA65DE/S

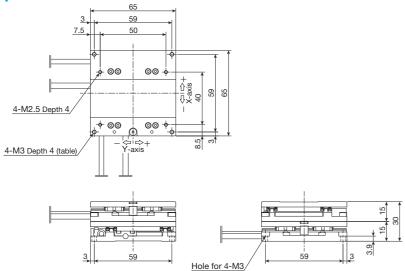


Note (1) Too deep insertion depth of the mounting bolt may affect the running performance of the moving table, so never insert a bolt longer than the depth of the through hole.

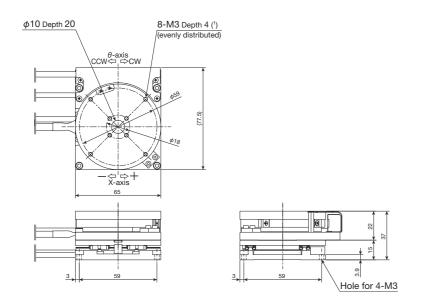
Remark: The text direction on the mark tube of the motor / limit cord may vary by product. The central hole of the  $\theta$ -table is a through hole.

# **IKO** Alignment Stage SA

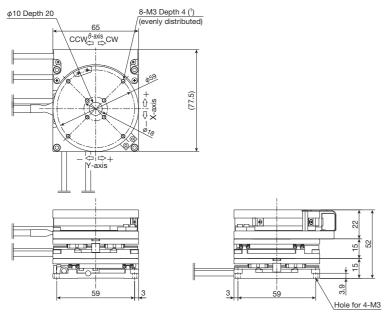
### SA65DE/XY



### SA65DE/XS



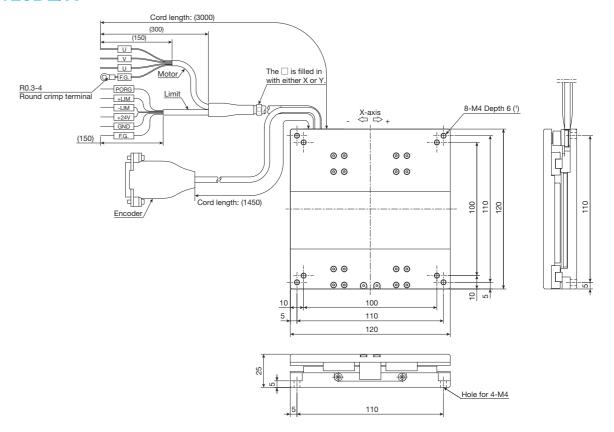
### SA65DE/XYS



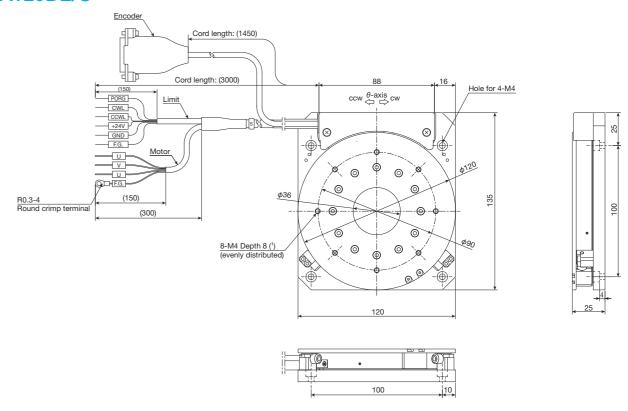
Note (1) Too deep insertion depth of the mounting bolt may affect the running performance of the moving table, so never insert a bolt longer than the depth of the through hole.

Remark: For the cable length, please see the dimension tables for SA65DE/X and SA65DE/S.

### SA120DE/X



### SA120DE/S

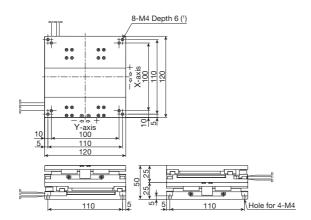


Note (1) Too deep insertion depth of the mounting bolt may affect the running performance of the moving table, so never insert a bolt longer than the depth of the through hole.

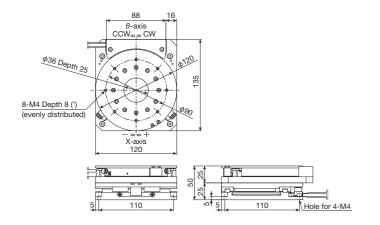
Remark: The text direction on the mark tube of the motor / limit cord may vary by product. The central hole of the  $\theta$ -table is a through hole.

# **IX** Alignment Stage SA

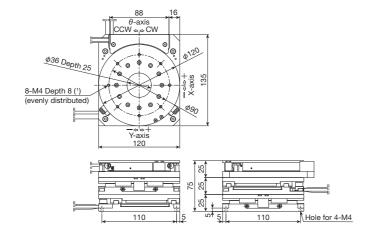
### SA120DE/XY



### SA120DE/XS



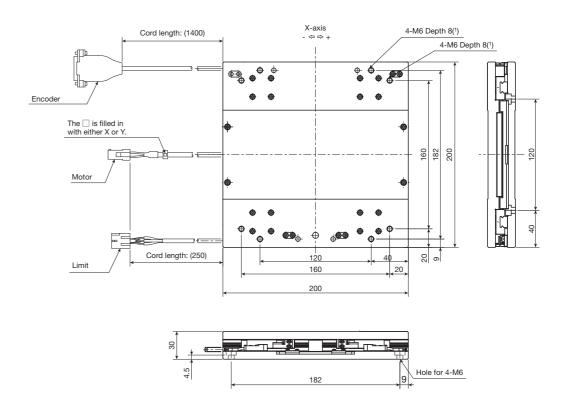
### SA120DE/XYS



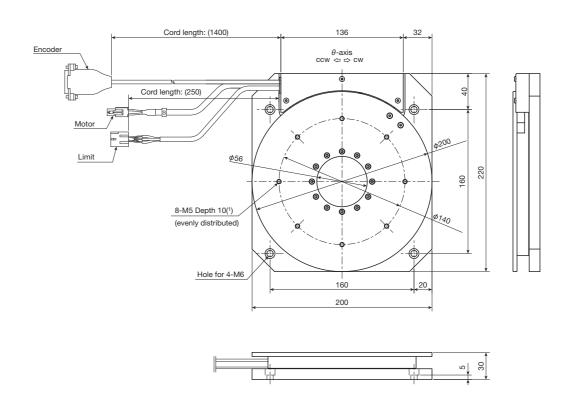
Note (1) Too deep insertion depth of the mounting bolt may affect the running performance of the moving table, so never insert a bolt longer than the depth of the through hole.

Remark: For the cable length, please see the dimension tables for SA120DE/X and SA120DE/S.

### SA200DE/X



### SA200DE/S

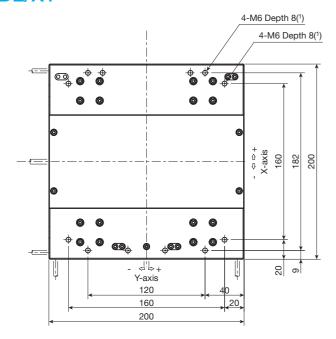


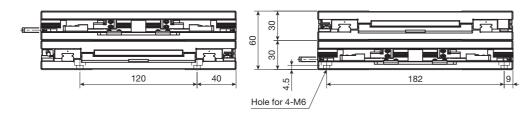
Note (1) Too deep insertion depth of the mounting bolt may affect the running performance of the moving table, so never insert a bolt longer than the depth of the through hole.

Remark: The central hole of the  $\,\theta$  -table is a through hole.

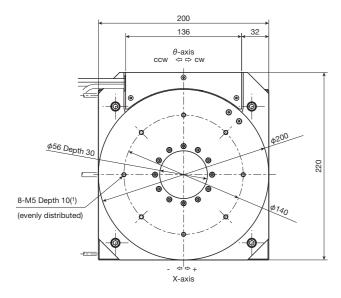
# **IX** Alignment Stage SA

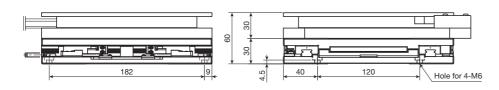
### SA200DE/XY





### SA200DE/XS

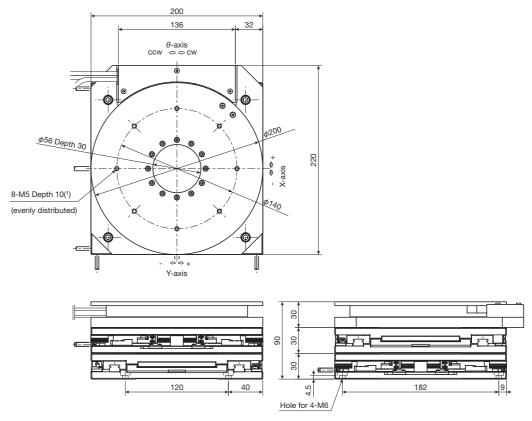




Note (1) Too deep insertion depth of the mounting bolt may affect the running performance of the moving table, so never insert a bolt longer than the depth of the through hole.

Remark: For the cable length, please see the dimension tables for SA200DE/X and SA200DE/S.

### SA200DE/XYS



Note (1) Too deep insertion depth of the mounting bolt may affect the running performance of the moving table, so never insert a bolt longer than the depth of the through hole.

Remark: For the cable length, please see the dimension tables for SA200DE/X and SA200DE/S.